

Constrained Schrödinger Dynamics and the Foundations of TDDFT

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18/03/2026

TDDFT = Time-Dependent Density Functional Theory

Goal : Describe the electronic dynamics submitted to a time-dependent external potential, using the one-body density ρ instead of the many-body wavefunction Ψ .

In practice : Use non-interacting fictitious electrons that reproduce ρ_Ψ .

1D Helium with Soft-Coulomb interaction

2 electrons in a singlet state

Interacting system

$$i\partial_t \Psi^S(t, x_1, x_2) = H(t) \Psi^S(t, x_1, x_2)$$

$$H(t) = \sum_{i=1}^2 h(t, x_i) + \frac{1}{\sqrt{(x_1 - x_2)^2 + 1}}$$

Kohn-Sham system

$$i\partial_t \varphi(t, x) = (h + V_{\text{Hxc}}[\rho_\varphi])(t, x) \varphi(t, x)$$

$$h(t, x) = -\frac{1}{2} \partial_x^2 - \frac{2}{\sqrt{x^2 + 1}} + V_{\text{elec}}(t, x)$$

Give ρ^S

Give ρ_φ



$V_{\text{Hxc}}[\rho_\varphi](t, x)$ is chosen so that $\rho^S = \rho_\varphi := 2|\varphi(t, x)|^2$.

Limitations in non-adiabatic regime

- Today, TDDFT is mostly used with **adiabatic approximations** :

$$V_{\text{Hxc}}(\rho_{\varphi})(t) = V_{\text{Hxc}}^{\text{LDA, GGA, ...}}(\rho_{\varphi}(t))$$

⇒ Works well in **near-adiabatic regimes** but fail in **non-adiabatic regimes** (e.g. charge-transfer processes).

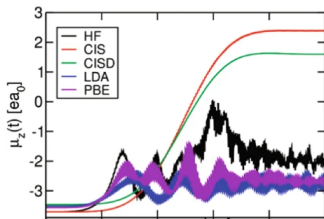
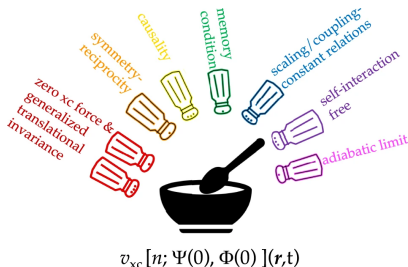


Figure 1 – Charge-transfer in LiCN.



- Main limit : **Absence of memory effects** : $V_{\text{Hxc}}(\rho_{\varphi})(t) = F(\rho_{\varphi}(t'), t' \leq t)$

Lionel Lacombe et Neepa T. Maitra. "Non-adiabatic approximations in time-dependent density functional theory : progress and prospects". In : (2023)

- **Time-dependent variational principle :**

Assuming the interacting density is known, how can one enforce a Kohn–Sham system to reproduce it ?

$\implies$ Can be achieved by introducing an additional real potential V_{Hxc} .

- **Time-dependent variational principle :**

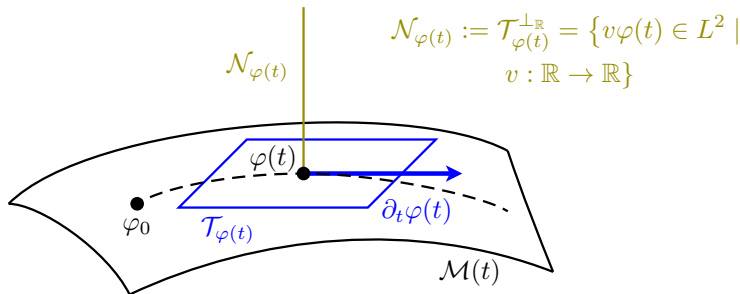
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Is the time-dependent variational principle the only natural principle for TDDFT ?

Geometric structure of the problem

We still consider the 1D helium system in a singlet state.
Assume you know the interacting density ρ^S :

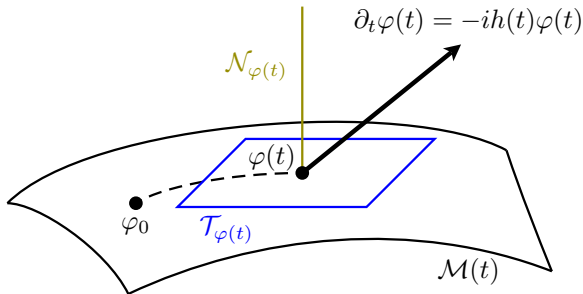


$$\mathcal{M}(t) := \{\varphi(t) \in L^2 \mid \rho_{\varphi}(t, x) = \rho^S(t, x)\}$$

$\mathcal{M}(t)$ is an infinite-dimensional **real** manifold.

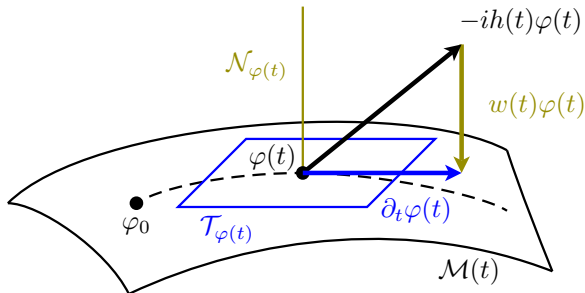
Geometric Principle (GP)

At time t , if no correction term is added, the trajectory leaves the manifold.



Geometric Principle (GP)

Project $-ih(t)\varphi(t)$ onto the real vector space $\mathcal{T}_{\varphi(t)}$!



$$\partial_t \varphi(t) + \underbrace{ih(t)\varphi(t)}_{\mathbb{R} \rightarrow \mathbb{R}} = w(t)\varphi(t) \in \mathcal{N}_{\varphi(t)}$$

$\Rightarrow$ purely imaginary "potential"

Time-dependent Variational Principle (TDVP)

A trajectory $\varphi(t) \in \mathcal{M}(t)$ satisfies the **TDVP** if it is a critical point of the action

$$\mathcal{A}[\eta] = \int_0^T \langle \eta(t) [i\partial_t - h(t)] \eta(t) \rangle_{L^2} dt$$

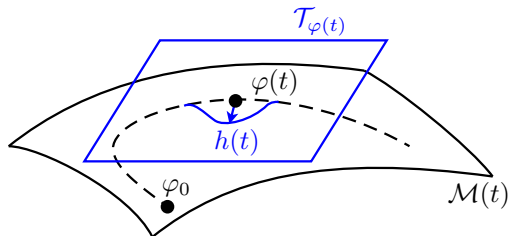
defined for paths $\eta(t) \in \mathcal{M}(t)$ such that $\eta(0) = \varphi(0)$ and $\eta(T) = \varphi(T)$.

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$$\partial_t \varphi(t) + \underbrace{ih(t)}_{\mathbb{R} \rightarrow \mathbb{R}} \varphi(t) = i v(t) \varphi(t) \in i\mathcal{N}_{\varphi(t)}$$

Two different principles

- **TDVP** $\implies$ Correction in $i\mathcal{N}_{\varphi(t)}$

$$i\partial_t\varphi(t, x) = -\frac{1}{2}\partial_x^2\varphi(t, x) + V_{\text{ext}}(t, x)\varphi(t, x) + V(t, x)\varphi(t, x)$$

- **GP** $\implies$ Correction in $\mathcal{N}_{\varphi(t)}$

$$i\partial_t\varphi(t, x) = -\frac{1}{2}\partial_x^2\varphi(t, x) + V_{\text{ext}}(t, x)\varphi(t, x) + iW(t, x)\varphi(t, x)$$

$\mathcal{M}(t)$ is not a Kähler Manifold !

$$\boxed{i\mathcal{N}_{\varphi(t)} \neq \mathcal{N}_{\varphi(t)}}$$

It is possible to mix TDVP and GP !

For example, if you have a TDVP approximation V , you can add it to your non-interacting system and then apply the GP :

$$\begin{cases} i\partial_t \varphi(t, x) = \left[-\frac{1}{2}\partial_x^2 + V_{\text{ext}}(t, x) + V(t, x) + iW(t, x) \right] \varphi(t, x), \\ \varphi(0, x) = \sqrt{\frac{\rho^S(0, x)}{2}} \end{cases}$$

where V and W are chosen to enforce $\rho_\varphi(t, x) = 2|\varphi(t, x)|^2 = \rho^S(t, x)$.

⇒ **Some degrees of freedom.**

Hydrodynamic picture

If $\varphi(t, x) = \sqrt{\frac{\rho^S(t, x)}{2}} e^{i\theta(t, x)}$, then the triplet (θ, V, W) solves

$$\left\{ \begin{array}{l} W = \frac{\partial_t \rho^S + \partial_x (\rho^S \partial_x \theta)}{2\rho^S}, \end{array} \right. \quad (1)$$

$$\left\{ \begin{array}{l} V = -\partial_t \theta - \frac{|\partial_x \theta|^2}{2} + \frac{\partial_x^2 \sqrt{\rho^S}}{2\sqrt{\rho^S}} - V_{\text{ext}}. \end{array} \right. \quad (2)$$

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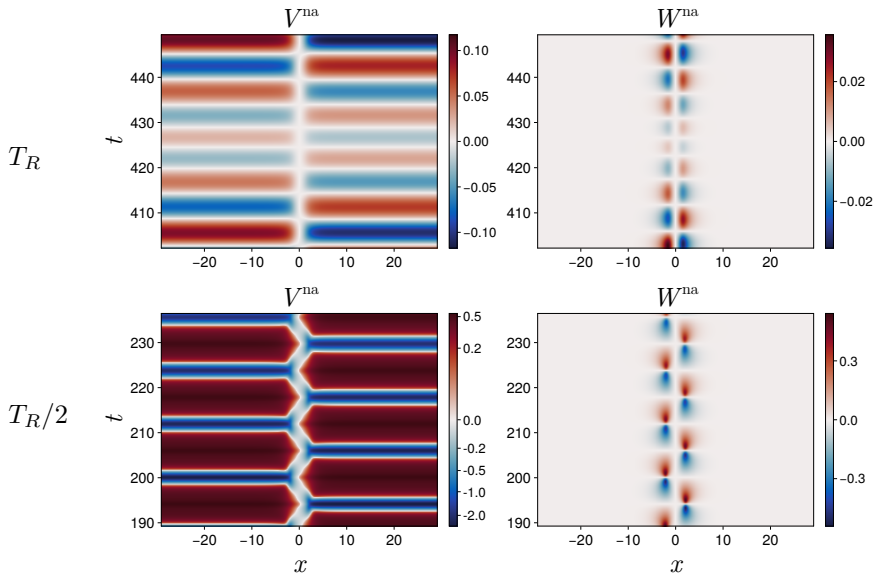
Several interesting cases :

- ❶ **TDVP** : $W = 0 \Rightarrow V^{\text{eKS}} := -\frac{1}{2} \left(\frac{j_\varphi}{\rho^S} \right)^2 - \int^x \partial_t \left(\frac{j_\varphi}{\rho^S} \right) + \frac{\partial_x^2 \sqrt{\rho^S}}{2\sqrt{\rho^S}} - V_{\text{ext}}.$
- ❷ **GP** : $V = 0 \Rightarrow$ Solve (2) to find θ and use (1) to deduce W .
- ❸ $\theta = 0$: No equation to solve !

$$V^{\text{eaKS}} := \frac{\partial_x^2 \sqrt{\rho^S}}{2\sqrt{\rho^S}} - V_{\text{ext}}, \quad W^{\text{na}} := \frac{\partial_t \rho^S}{2\rho^S}.$$

We want to compare W^{na} with $V^{\text{na}} := V^{\text{eKS}} - V^{\text{eaKS}}.$

Rabi Oscillation in 1D Helium : $\psi_{\text{gs}} \xrightarrow{T_R} \psi_{\text{exc}} \xrightarrow{T_R} \psi_{\text{gs}} \xrightarrow{T_R} \dots$



- [Éric Cancès et al.](#) *Geometric theory of constrained Schrödinger dynamics with application to time-dependent density-functional theory on a finite lattice.* 2026. arXiv : 2601.07719. url : <https://arxiv.org/abs/2601.07719>
 - Abstract constrained Schrödinger equation on a lattice for arbitrary observables.
 - TDVP-representable $\implies$ GP-representable
- [Éric Cancès et al.](#) *Geometric Time-Dependent Density Functional Theory.* 2026. arXiv : 2601.07724. url : <https://arxiv.org/abs/2601.07724>
 - Introduce formally the continuous case.
 - Formulation of orbital free TDDFT.

Thank you for your attention !